EUROPEAN PATENT OFFICE TOO1POG525

Patent Abstracts of Japan

PUBLICATION NUMBER

07141002

PUBLICATION DATE

02-06-95

APPLICATION DATE

16-11-93

APPLICATION NUMBER

05308612

APPLICANT: YAMATAKE HONEYWELL CO LTD;

INVENTOR: AKANO SHINICHI;

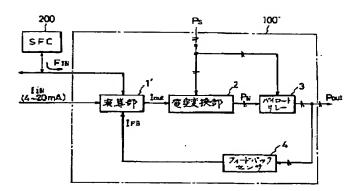
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G05B 11/36 F15B 5/00 F15B 9/07

G05D 7/06

TITLE

POSITIONER



ABSTRACT :

PURPOSE: To correct a characteristic curve based on an actually measured value when the difference between the actually measured value of a controlled system received in online made and a target value calculated from the built-in characteristic curve is larger than a prescribed value by calculating that difference at the time of correction.

CONSTITUTION: At the time of correction, an operator sets an ultrasonic flow meter, actually measures a process flow rate F and imparts the actually measured value FIN of the process flow rate to an arithmetic part 1' of an electropneumatic positioner 100' in online mode. When the actually measured value FIN is inputted, the arithmetic part 1' reads an input electric signal IIN at that time. At input time, the input electric signal IIN is applied for 50%, a target value FOUT of the process flow rate corresponding to the read input electric signal IIN is calculated according to the built-in characteristic curve, the difference between the target value FOUT and the measured value FIN is calculated and when the difference is more than the fixed value, the built-in characteristic curve is corrected by the arithmetic part 1'. Thus, the accuracy of measurement from a present value at any adjacent position is improved, and the process flow rate F can be controlled with high accuracy.

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